

# ANISOTROPIC COMPUTATIONAL DESCRIPTION OF BONY ELEMENTS: A JAW STUDY



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CT data



## Aim

Nowadays, the need of **computational clinical tools** for intervention planning and effectiveness evaluation is increasing in demand. High accuracy, patient specificity and real-time results are crucial factors. The **aim** of the research activities consists in the implementation of an almost **automatic procedure** for the characterisation of bone tissue mechanical behaviour starting from *in vivo* CT data. The procedure is customized for the patient and the bony element.

## Materials and Methods

Steps of the implemented procedure:

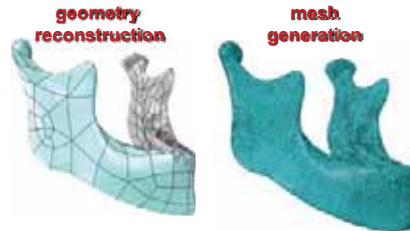
### A. CT segmentation and virtual solid model.

### B. Definition of FE model.

The virtual solid model is imported into the FE pre-processor Abaqus CAE 2018 (Dassault Systèmes Simulia Corp., Providence, RI). A standard mesh composed by unstructured four-node tetrahedral elements is defined. Different mesh seeds are assumed.

### C. Material property extraction.

- constitutive tensors are based on a micromechanics formulation [1]. The non-zero components of the pure cortical bone tensor are customized for the jaw [2].
- principal material directions are defined as the eigenvectors of the HU "inertia" matrix.



$$\mathbf{M} = \begin{bmatrix} \sum_i HU_i (y_i^2 + z_i^2) & -\sum_i HU_i x_i y_i & -\sum_i HU_i x_i z_i \\ -\sum_i HU_i y_i x_i & \sum_i HU_i (x_i^2 + z_i^2) & -\sum_i HU_i y_i z_i \\ -\sum_i HU_i z_i x_i & -\sum_i HU_i z_i y_i & \sum_i HU_i (x_i^2 + y_i^2) \end{bmatrix}$$

### D. Material assignment.

Different mapping strategies are implemented, which consider:

- the material properties of the nearest voxel (NVS, Nearest Voxel Strategy);
- the averaged material properties of the three nearest voxels (TNVS, Three Nearest Voxels Strategy).

### E. Discrepancy quantification.

Error Rate =  $\sqrt{\frac{1}{N} \sum_{i=1}^N \left( \frac{c^{ME,i} - c^{V,i}}{c^{V,i}} \right)^2}$ , N is the number of CT voxels,  $c^{(ME,i)}$  is a property of the  $i$ -th element of the mesh, while  $c^{(V,i)}$  is the property of the corresponding voxel. The property  $c$  is the Young's elastic modulus along the major stiffness direction.

### HU "inertia" matrix

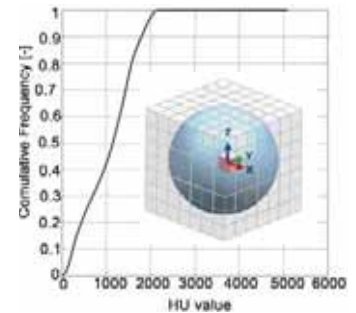


Fig.1: Plot of the cumulative frequency analysis and spherical voxel set used for the detection of the principal material directions.

## Results

- The procedure respects the differentiation between trabecular and cortical bone, detectable from CT scan (Fig. 2).
- The NVS strategy provides the better results but the mesh element dimension affect the results (Fig. 3).

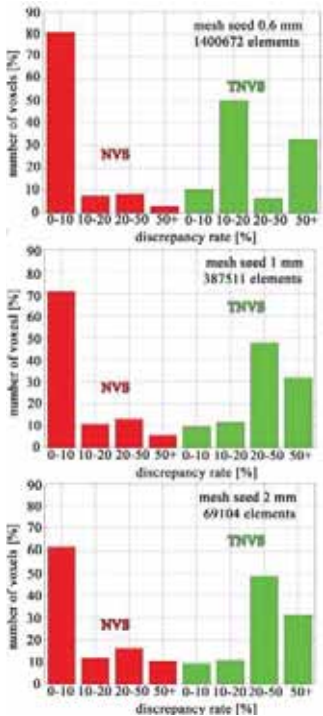


Fig.3: Histograms of the estimated discrepancy rate for different mean element sizes.

- The detection of the maximum principal material direction is proposed in Fig. 5.
- Validation of the biomechanical model by conserving a structural test [4] (Fig.4).

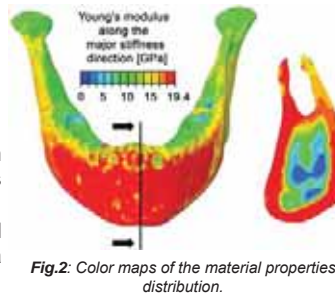


Fig.2: Color maps of the material properties distribution.

### biomechanical structural test

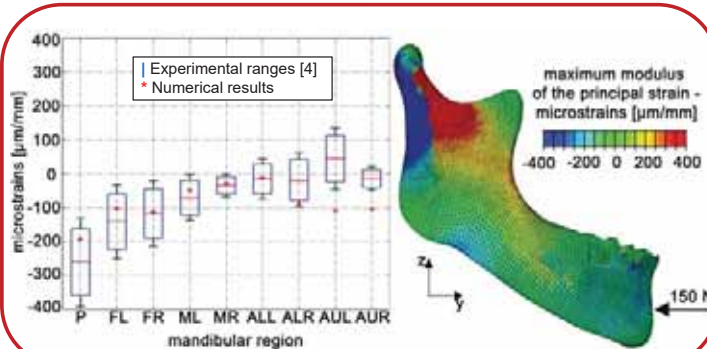


Fig.4: Comparison between experimental ranges [4] and numeric results in terms of microstrains. P - Pogonion, FL - mental Foramen Left, FR - mental Foramen Right, ML - Molar region Left, MR - Molar region Right, ALL - mandibular Angle Lower Left, ALR - mandibular Angle Lower Right, AUL - mandibular Angle Upper Left, AUR - mandibular Angle Upper Right (a).

### detection of the directions of anisotropy

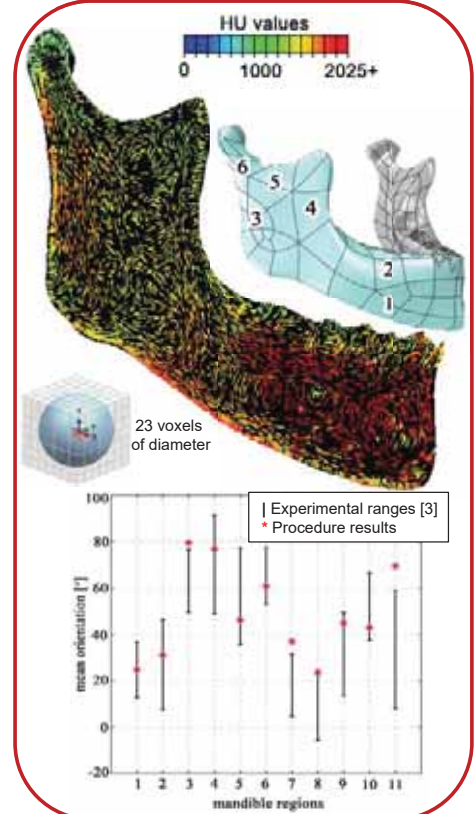


Fig.5: Detection of the direction of anisotropy along the major stiffness direction.

## Discussion

The achieved results point out the capability of the procedure in supplying **subject specific models of bony structures** starting from *in vivo* CT data. The good matches with experimental results highlight the procedure's great potentialities and its accuracy and almost automatism give the basis to develop a clinical tool. There are still open questions principally regard the size of the neighbourhood for the identification of material principal directions.

## References

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